



Brüel & Kjær Vibro

# Product Specifications

## VC-6000 Monitoring System

### Monitoring Module – SM-610-112

**4x Process, 1x Speed, 3x Axial Displacement Channels, 8x DC Outputs, 8x Relays**

The VC-6000 Monitoring System hardware is used for both stand-alone safety monitoring and condition monitoring using the Compass 6000 monitoring software modules and database. The VC-6000 offers various standard monitoring modules, power supply modules and communication modules. This Product Specification describes the SM-610-112.

#### Applications

The SM-610 series of VC-6000 Monitoring Modules are designed to provide protective monitoring of various types of industrial machines. The SM-610-112 is specifically designed for monitoring process parameters and axial displacement of a machine. It can also be used to monitor speed.

#### General Description

The features and functions common to all SM-610 Monitoring Modules are briefly listed below. Please refer to the VC-6000 Product Specifications (BPS 0044) for more information.

- Interfacing with the CI-6xx Communication Modules
- High speed digital signal processor
- Relay outputs (logic controlled)
- OK-relay status indication
- Extensive local LED indication
- Flash memory for storing settings and local logbook
- High speed reaction time - 10ms
- Alarm limits with programmable hysteresis and response delay time
- Global trip multiply and override
- Extensive self-monitoring functions
- System bus interface to other modules
- Buffered vibration outputs



#### Inputs

- 4x process input signals
- 3x axial displacement signals
- 1x speed/phase reference signal

#### Outputs

- 8x analogue DC output
- 8x relays (4x Danger, 4x Alert):
  - 4x axial – 1-out-of-2 voting logic
  - 2x axial – 2-out-of-3 voting logic
  - 2x process – 1-out-of-8 voting logic

#### Measurements

- 7x DC – 3x axial, 4x process
- 1x RPM

### Input Channel Configuration Combinations

	Monitoring Module – SM-610-112 4x Process, 1x Speed, 3x Axial Displacement Channels, 8x DC Outputs, 8x Relays																	
No. of Inputs <sup>1</sup>	Channel Types															Additional Measurements		Relay's
	Dual-point Vibr. <sup>2</sup> (ISO)	DC-out	Single-point Vibr <sup>2</sup> (ISO)	DC-out	Axial Pos.	DC-out	Speed	DC-out	Rod Drop	DC-out	Rel. Exp.	DC-out	Eccentricity	DC Input (Process, Absolute Exp)	DC-out	Bin. in	Vector <sup>3</sup>	BP
8					3	3	1	1						4	4			2x 1oo3 for Axial or 2x 1oo2 for 2 of the Axial Pos. 2x 1oo4 for Radial
<sup>1</sup> The number of input signals is the sum total of the channels shown in yellow.																		

<sup>1</sup> The number of input signals is the sum total of the channels shown in yellow.

### Signal Flow Diagrams

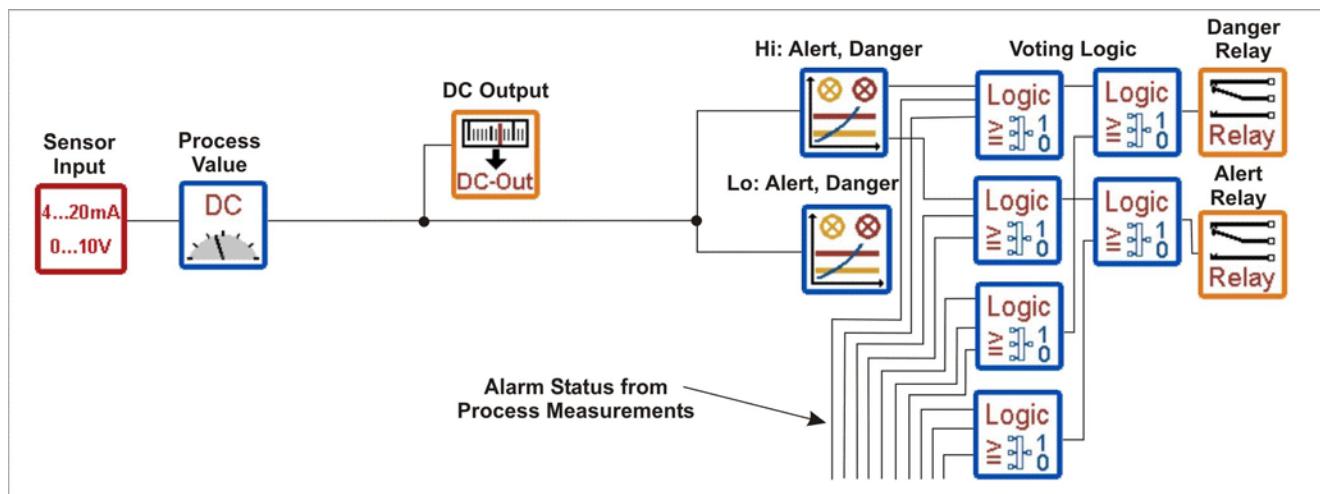


Figure 1. Process inputs (4 channels). Separate 1-out-of-8 voting logic is used for all process Alert and Danger relay control.

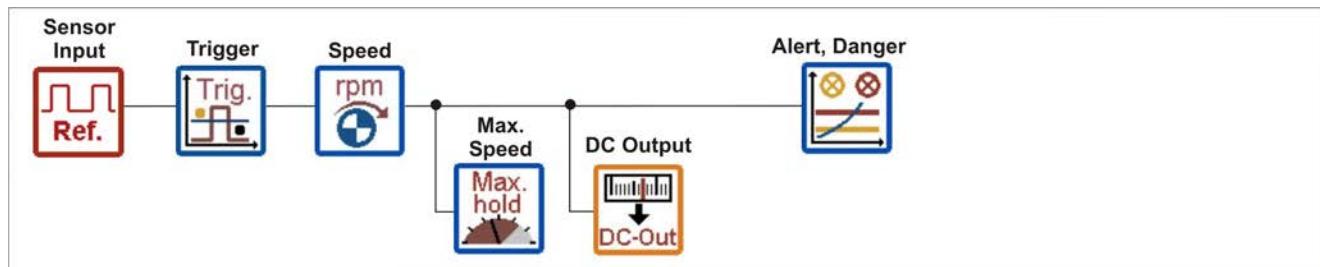


Figure 2. Speed/phases reference sensor input (1 channel).

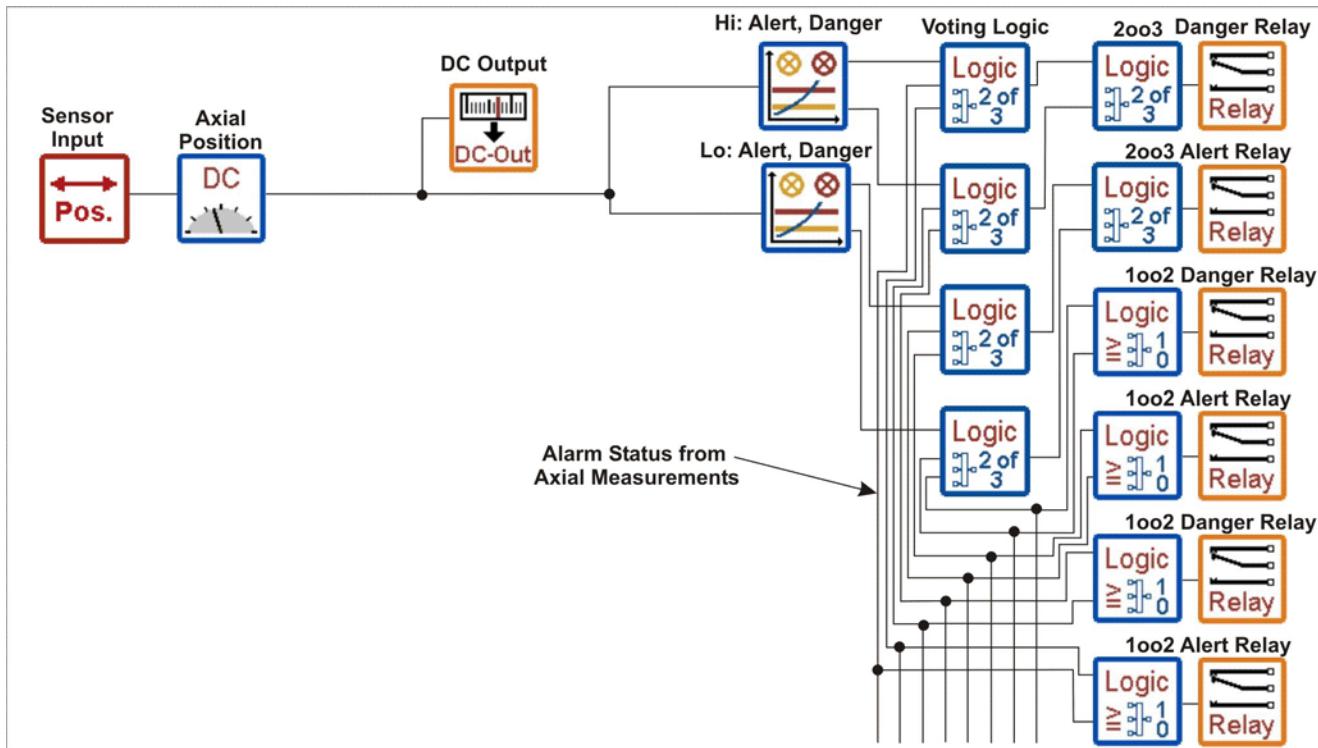


Figure 3. Axial displacement inputs (3 channels). Separate voting logic is used for Alert and Danger relay control: 1-of-2 voting logic (4 relays per 3 axial measurements) and 2-of-3 voting logic (2 relays per 3 axial measurement).

## Technical Specifications

The specifications given below are specific for the SM-610-112 Monitoring Module. See the VC-6000 Product Specifications for features and functions common to all SM-610 Monitoring modules.

### Axial Displacement Sensor Inputs

Input voltage range ..... -21.5 to -1V  
 Input frequency range ..... DC to 20kHz  
 Input impedance ..... >800kΩ  
 Gain ..... 1 ( $\pm 0.75\%$ )

#### Common mode rejection:

DC to 10kHz ..... typically 90dB  
 10kHz to 100kHz ..... typically 85dB

#### Sensor power:

Sensor supply ..... -24VDC  $\pm 2\%$   
 Maximum current ..... 30mA

### Process Inputs

Input current range .....  $\pm 30\text{mA}$   
 Input voltage range .....  $\pm 14\text{V}$   
 Input frequency range ..... DC to 20kHz  
 Input impedance (voltage input) .....  $200\text{k}\Omega$   
 Input current load .....  $100\Omega$   
 Sensitivity ..... adjustable  
 Gain ..... 1 ( $\pm 1\%$ )  
 Sensor power ..... external

### Speed/Phase Reference Sensor Inputs

Input voltage range ..... -21.5 to -1V  
 Input frequency range ..... DC to 20kHz  
 Input impedance ..... >800kΩ  
 Gain ..... 1 ( $\pm 0.75\%$ )

#### Common mode rejection:

DC to 10kHz ..... typically 90dB  
 10kHz to 100kHz ..... typically 85dB

**Sensor power:**

Sensor supply ..... -24VDC ±2%  
 Maximum current ..... 30mA

**Voltage output:**

Voltage range ..... 0 to 10V  
 Minimum output load ..... 1kΩ  
 Accuracy ..... <1.3% of measured value  
 Offset ..... <9.5mV

**Analogue DC Outputs**

**Current output:**

Current range ..... 4 to 20mA or 0 to 20mA  
 Maximum output load ..... 500Ω  
 Accuracy ..... <2.4% of measured value  
 Offset ..... <20µA

**Relay Outputs**

Nominal working voltage ..... 24V  
 Maximum current ..... 100mA

**Measurements**

Meas. Name	Frequency Range	Measuring Time	Detection	Alarm Limits	Measuring Range	Units <sup>1</sup>	Accuracy (25°C, 80Hz, 0-Peak)
DC (process)	-	Adjustable 10ms to 100s	-	2x Alert, 2x Danger	±14V	V <sup>2</sup>	±(9.0mV+ 1.0% of measured value)
					±30mA	mA <sup>2</sup>	±(0.2µA+ 1.0% of measured value)
DC (axial)	-	Adjustable 10ms to 100s	-	2x Alert, 2x Danger	2000µm	µm	±(10.0µm + 1.0% of measured value)
RPM (also Max. RPM)	Signal slope: +/- Trigger level <sup>3</sup> (manual or automatic): -21.5 to -1V; adjustable in steps of 0.1V  Hysteresis: 0 to 25; adjustable in steps of 0.1	Adjustable 10ms to 100s	RPM	1x Alert, 1x Danger	0.06 to > 1200000 RPM RPM multiplier and divider adjustable from 1 to 99999	RPM	Speed >10000rpm: ±0.01% of measured value Speed 100 to10000 rpm: ±1 rpm Speed < 100 rpm: ±0.1 rpm (one pulse per revolution)

<sup>1</sup> Metric and imperial units can be used; Metric units are shown only as an example.

<sup>2</sup> User-defined units. Sensor input signal units indicated here

<sup>3</sup> Please refer to the sensor input for the allowed input signal.

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